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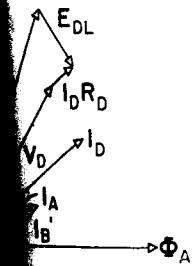
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SOME ELECTROMAGNETIC PARADOXES

BY

PARRY MOON¹ AND DOMINA EBERLE SPENCER²

1. INTRODUCTION

Electromagnetic theory is undoubtedly one of the most imposing theoretical edifices reared by the mind of man. It is a work of genius—of Maxwell, Hertz, Lorenz, Lorentz, Poincaré, Einstein. Yet it does not form a logical whole, as evidenced by numerous paradoxes.

Classical theory is built up of pieces, each admirable in its way but not fitting too comfortably into the whole. Sometimes we pretend that flux lines have physical existence: we visualize them as rubber bands pulling on conductors or as filaments that are cut by moving wires. At other times we are unable to decide whether these flux lines are moving or stationary, and we fall back on Maxwell's equations which express the phenomena in terms of the rather abstract vectors \mathbf{E} , \mathbf{D} , \mathbf{B} , \mathbf{H} . At still other times, we find it desirable to use retarded potentials. Einstein's relativity may also be introduced.

Unfortunately, these various methods of handling a problem do not always lead to the same conclusion. Hence the paradoxes! If one knows the correct result, he can usually find a part of classical theory that will give him the answer. And he can always justify his choice by some plausible argument. But an equally logical argument can be found for other approaches that may give erroneous results. As Ko-Ko says, "Here's a state of things, here's a how-de-do!"

In the following pages, we consider a number of paradoxes. In each case, the problem is stated and a solution is given. This solution is in accordance with classical theory but does not agree with experiment. It is the kind of solution that might be obtained by a scrupulous but inexperienced student. The reader may amuse himself by finding a classical approach that gives the correct answer.

Each problem is also solved by employing the interparticle method developed by Coulomb, Ampère, Gauss, and Ritz. This method, unlike the Maxwell formulation, can be summarized (1)³ in a *single equation and this equation gives unambiguous results*. In the new electrodynamics, no paradoxes have been found.

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³ The boldface numbers in parentheses refer to the references appended to this paper.

2. THE NEW ELECTRODYNAMICS

The non-Maxwellian approach subsumes the whole of electrody-
namics under the single equation,

$$\mathbf{F}_2/Q_2 = \mathbf{a}_r \frac{Q_1}{4\pi\epsilon c^2 r^2} [\mathbf{v} \cdot \mathbf{v} - \frac{3}{2}(\mathbf{a}_r \cdot \mathbf{v})^2] - \frac{Q_1}{4\pi\epsilon c^2 r} \frac{d}{dt} \mathbf{v}(t - r/c) - \mathbf{a}_r \frac{1}{4\pi\epsilon} \frac{\partial}{\partial r} \left[\frac{1}{r} Q_1(t - r/c) \right]. \quad (1)$$

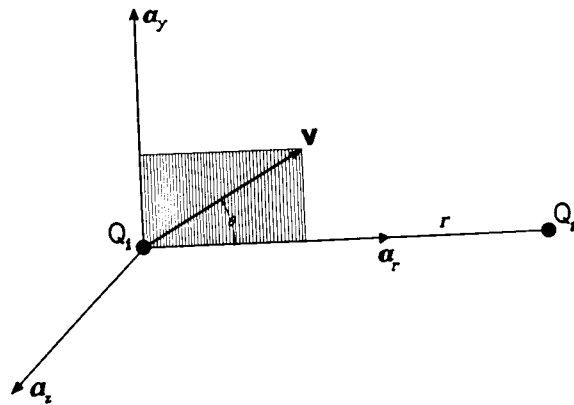


FIG. 1. Two charged particles.

The notation is indicated in Fig. 1. The unit vector \mathbf{a}_r points from Q_1 to Q_2 . Angles are measured counter-clockwise from \mathbf{a}_r . Vector \mathbf{v} is the relative velocity of Q_1 with respect to Q_2 . Equation 1 applies at all ordinary velocities: in fact, it is reasonably accurate up to approximately half the velocity of light. At higher velocities, corrections must be applied.

Note that the magnetic-field concept is completely eliminated and \mathbf{B} , \mathbf{H} , and μ do not occur. The usual "magnetic" forces and "flux-cutting emf.'s" are handled by the first term of Eq. 1 which depends on the relative velocity of charges. The second term depends on the acceleration of charges, while the third term is related to Maxwell's displacement current and includes the Coulomb force as a special case (1). For moderate frequencies and distances, retardation may be neglected and Eq. 1 reduces to

$$\mathbf{F}/Q_2 = \mathbf{a}_r \frac{Q_1}{4\pi\epsilon r^2} \left(\frac{v}{c}\right)^2 [1 - \frac{3}{2} \cos^2 \theta] - \mathbf{a}_r \frac{Q_1}{4\pi\epsilon c^2 r} \frac{dv}{dt} + \mathbf{a}_r \frac{Q_1}{4\pi\epsilon r^2}. \quad (1a)$$

Equations 1 and 1a apply to the force between charges Q_1 and Q_2 , Fig. 1. These equations are easily extended (1) to give the force be-

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For a current element I
Eq. 1 gives

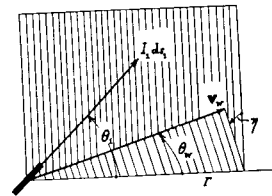


FIG. 2. Current element charged particle.

$$d\mathbf{F}/Q_2 = \mathbf{a}_r \frac{|I_1|}{4\pi\epsilon c^2 r^2} = \mathbf{a}_r \frac{|I_1| v_w ds_1}{4\pi\epsilon c^2 r^2} [2$$

Here the sense of ds_1 is of the material wire w directly proportional t
parently, this addition will be ignored in this

The first term of \mathbf{F} (Fig. 3). This Ampère

$$d^2\mathbf{F} = - \mathbf{a}_r \frac{|I_1||I_2|}{4\pi\epsilon c^2 r^2}$$

This force is independent of the material wire w
Equation 3 is with no terms neglected

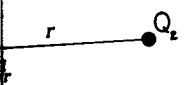
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$$\frac{\partial}{\partial r} \left[\frac{1}{r} Q_1(t - r/c) \right] \quad (1)$$



articles.
unit vector \mathbf{a}_r points from Q_1 towards Q_2 . Vector \mathbf{v} is the velocity of the charge. Equation 1 applies at all ordinary velocities up to approximately half the speed of light. Corrections must be applied. The magnetic force is completely eliminated and the electric force is completely eliminated and "magnetic" forces and "flux-tube" forces of Eq. 1 which depends on the acceleration of the charge are related to Maxwell's displacement current as a special case (1). For radiation may be neglected and

$$\mathbf{a}_r \frac{Q_1}{4\pi\epsilon c^2 r} \frac{dv}{dt} + \mathbf{a}_r \frac{Q_1}{4\pi\epsilon r^2} \quad (1a)$$

force between charges Q_1 and Q_2 , is given by (1) to give the force be-

tween current elements or between a current element and a charge. For a current element $I_1 ds_1$ and a charge Q_2 (Fig. 2), the first term of Eq. 1 gives

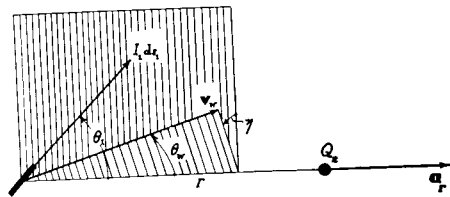


FIG. 2. Current element and charged particle.

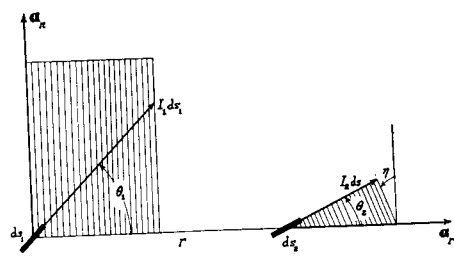


FIG. 3. Two current elements.

$$d\mathbf{F}/Q_2 = \mathbf{a}_r \frac{|I_1|}{4\pi\epsilon c^2 r^2} [2(\mathbf{a}_r \times \mathbf{v}_w) \cdot (\mathbf{a}_r \times ds_1) - (\mathbf{a}_r \cdot \mathbf{v}_w)(\mathbf{a}_r \cdot ds_1)]$$

$$= \mathbf{a}_r \frac{|I_1| v_w ds_1}{4\pi\epsilon c^2 r^2} [2 \sin\theta_w \sin\theta_1 \cos\eta - \cos\theta_w \cos\theta_1] \quad (2)$$

Here the sense of ds_1 is the direction of the current, and \mathbf{v}_w is the velocity of the material wire with respect to Q_2 . Equation 1 also yields a term directly proportional to the drift velocity \mathbf{v}_1 of the electrons (2). Apparently, this additional force is always too small to be measured, so it will be ignored in this paper.

The first term of Eq. 1 can be applied also to two current elements (Fig. 3). This Ampère force is

$$d^2\mathbf{F} = - \mathbf{a}_r \frac{|I_1||I_2|}{4\pi\epsilon c^2 r^2} [2(\mathbf{a}_r \times ds_1) \cdot (\mathbf{a}_r \times ds_2) - (\mathbf{a}_r \cdot ds_1)(\mathbf{a}_r \cdot ds_2)] \quad (3)$$

This force is independent of the relative velocity of the material elements. Equation 3 is a rigorous deduction from the first part of Eq. 1, with no terms neglected.

The remainder of the paper is devoted to a consideration of a few of the paradoxes that occur in conventional electromagnetic theory.

3. ELECTRON BEAMS

Statement

Parallel electron guns produce two identical electron beams in a long, evacuated tube. Initial velocity of the electrons with respect to the laboratory is \mathbf{v}_0 . What is the magnitude and direction of the force on the electrons?

A Classical Solution

The argument may be stated rather neatly in the form of a classical syllogism:

- (a) A stream of electrons is equivalent to a current (Rowland's experiment).
- (b) Parallel currents in the same direction attract each other, as proved experimentally by the behavior of parallel, current-carrying wires.
- (c) Therefore, the electron beams will attract each other and will tend to converge.

The current in one beam is

$$I = -NA|Q_e|v,$$

where

- N = number of free electrons per unit volume,
 A = cross-sectional area of the beam,
 $|Q_e|$ = magnitude of electronic charge.

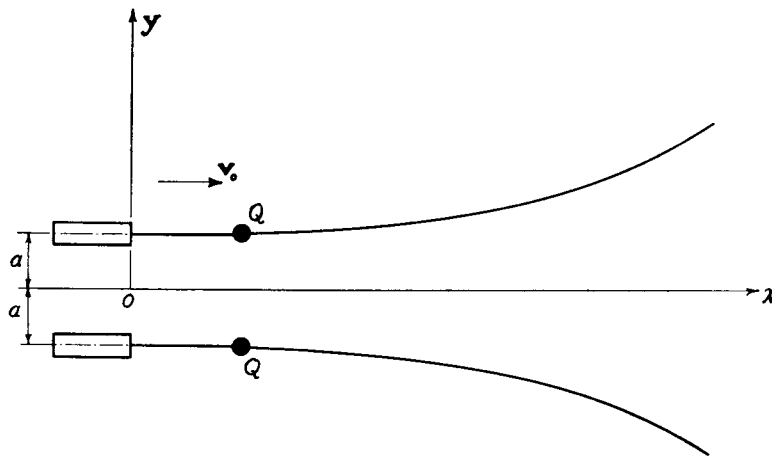


FIG. 4. Electron beams. Electrons are emitted at $x = 0$ with velocity v_0 in the x -direction.

This current produces a magnetic flux density at the other beam,

$$B = \frac{\mu_0 I}{2\pi a},$$

where a is the distance between the axes of the beams. The resulting force per unit length is

$$F/l = BI = \frac{\mu_0 I^2}{2\pi a} = \frac{N^2 A^2 |Q_e|^2}{2\pi \epsilon \epsilon^2 a} v^2. \quad (4)$$

The force is perpendicular to the direction of motion, and the result that is certain.

For other solutions, see (3), where a long and short Leacock's rider who moves in opposite directions."

Electrodynamic Solution

Consider two charges moving in the x -direction (Fig. 4). The distance x from the origin is the same in both frames, but the relative velocity is zero. Thus Eq. 1 reduces to the upper particle is

For a coordinate system moving with the particles, the electrostatic repulsion is stationary. The electric field is as found in practice.

The force, Eq. 5,

or

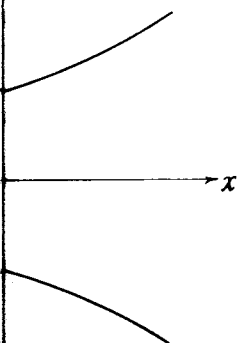
But $x = v_0 t$; so the distance in the coordinate system, is

Thus the problem is solved by elementary mechanics. On the other hand, in the absence of a magnetic field, such questions do not require relativity needed.

Equations 1 and 2 show the reaction terms. Strictly speaking, the velocity and acceleration are easily accomplished since both terms in

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the beams. The resulting

$$\frac{Q_e^2}{a} v^2. \tag{4}$$

The force is perpendicular to \mathbf{v} and tends to pull the beams together; a result that is certainly not in accord with experiment.

For other solutions, the reader is referred to *Electrical Engineering* (3), where a long and inconclusive discussion reminds one of Stephen Leacock's rider who "leaped on his horse and dashed madly off in all directions."

Electrodynamic Solution

Consider two charged particles moving in parallel paths in the x -direction (Fig. 4). Each particle has a charge Q and is at the same distance x from the origin. The velocity is v_0 with respect to the laboratory, but the *relative* velocity of one charge with respect to the other is zero. Thus Eq. 1 reduces to the Coulomb equation, and the force on the upper particle is

$$\mathbf{F} = a_y \frac{Q^2}{4\pi\epsilon r^2}. \tag{5}$$

For a coordinate system moving with the charges, *the force is an ordinary electrostatic repulsion which is exactly the same as if the charges were stationary.* The electron beams of Fig. 4 will therefore tend to diverge, as found in practice.

The force, Eq. 5, will accelerate the particles in the y -direction:

$$F = m \frac{d^2y}{dt^2}$$

or

$$y = a + \frac{F}{m} t^2.$$

But $x = v_0 t$; so the path of the upper particle referred to a stationary coordinate system, is a parabola:

$$y = a + (F/mv_0^2)x^2. \tag{6}$$

Thus the problem is a very simple one, requiring only a knowledge of elementary mechanics and of Coulomb's equation. Classical treatment, on the other hand, introduces puzzling questions such as the presence or absence of a magnetic field, depending on the motion of the observer. Such questions do not arise in the new electrodynamics, nor is Einstein's relativity needed.

Equations 1 and 6 do not apply for $v \rightarrow c$ without additional correction terms. Strictly speaking, corrections should be made also for the velocity and acceleration in the y -direction. This modification is easily accomplished by use of the first and second terms of Eq. 1; but since both terms include c^2 in the denominator, their effect is ordinarily

negligible. For the electron-beam problem, the Coulomb repulsions of all electrons in the beams should be considered. But this would not change the foregoing general conclusion that *the force is merely a Coulomb repulsion and is never the attraction obtained with parallel currents.*

4. LONGITUDINAL MOTION

Statement

A flexible conductor AA' , Fig. 5, carries a direct current I_1 . Near A is a long, straight conductor C carrying a steady current I_2 . The

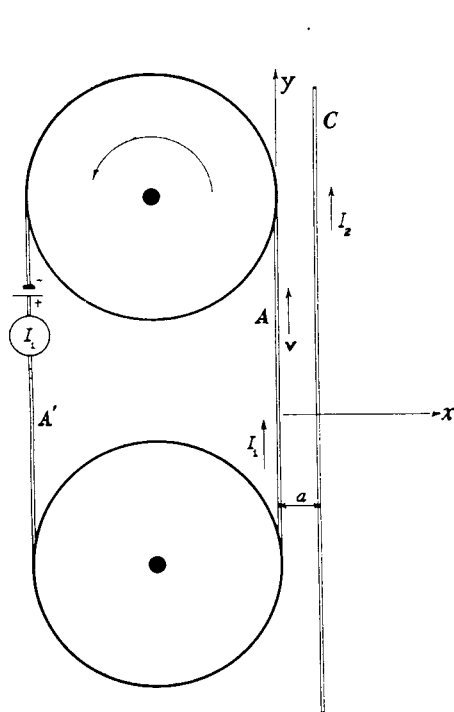


FIG. 5. Determine the force between conductors A and C when A is in uniform longitudinal motion.

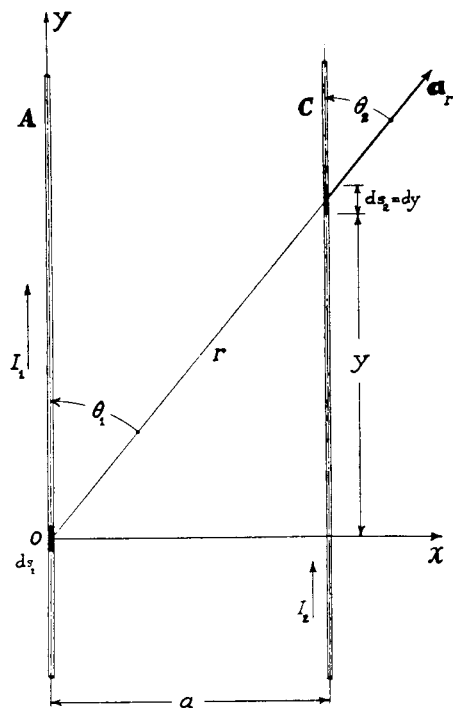


FIG. 6. Analysis of Fig. 5.

distance a is small compared with the other dimensions, so the effects of the return conductors may be neglected. What is the force per unit length, exerted on conductor C ?

A Classical Solution

First consider AA' stationary. The magnetic flux density at C , caused by current I_1 , is

$$B = \frac{\mu_0 I_1}{2\pi a}$$

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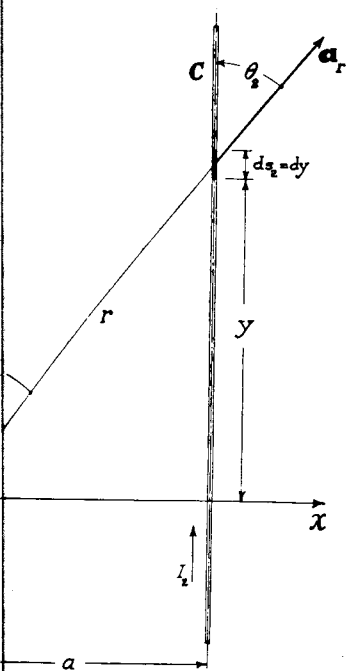


FIG. 6. Analysis of Fig. 5.

dimensions, so the effects
What is the force per unit

magnetic flux density at C ,

The force on C , according to Faraday's relation, is

$$F_2 = BI_2$$

or

$$F_2/l = \frac{\mu_0 I_1 I_2}{2\pi a} = \frac{I_1 I_2}{2\pi \epsilon c^2 a} \tag{7}$$

The current in A is

$$I_1 = N_1 A_1 |Q_e| v_1,$$

where the symbols are as in Section 3 and v_1 is the magnitude of the drift velocity of the electrons in A .

Now allow A to move longitudinally at velocity v . According to Rowland's experiment, moving charges constitute a current, so the effective current is not I_1 but is

$$\begin{aligned} I_1' &= N_1 A_1 |Q_e| (v_1 - v) \\ &= I_1 \left(\frac{v_1 - v}{v_1} \right). \end{aligned}$$

Replacing I_1 in Eq. 7 by I_1' , we obtain

$$F_2/l = \frac{I_1 I_2}{2\pi \epsilon c^2 a} \left(\frac{v_1 - v}{v_1} \right) \tag{8}$$

Since v may easily exceed $10^4 v_1$, we can obtain with the moving conductor a force 10,000 times as great as that obtained with the stationary conductor. What is wrong with this prediction?

Electrodynamic Solution

It is easily proved that Eq. 3 is independent of conductor velocity. Thus the force is independent of v and is obtained by integration of Eq. 3. From Fig. 6, $\theta_1 = \theta_2 = \theta$, $\eta = 0$, and the force on element ds_2 is

$$\begin{aligned} d\mathbf{F}_2 &= -\mathbf{a}_x \frac{|I_1||I_2|ds_2}{4\pi \epsilon c^2} \int_{-\infty}^{\infty} \frac{[2 \sin^2\theta - \cos^2\theta] \sin\theta}{r^2} dy \\ &= \mathbf{a}_x \frac{|I_1||I_2|ds_2}{2\pi \epsilon c^2 a}. \end{aligned}$$

The force is independent of the position of ds_2 in the y -direction, so the force per unit length on C is

$$\mathbf{F}_2/l = \mathbf{a}_x \frac{|I_1||I_2|}{2\pi \epsilon c^2 a} \tag{9}$$

which agrees with Eq. 7.

The only difference between the classical and the electrodynamic solution is that Eq. 7 may leave one with doubts as to possible effects of the motion of the conductor, while Eq. 1 leads directly and conclusively to Eq. 9, *irrespective of longitudinal motion.*

Statement

5. INDUCED EMF.

A moving conductor AA' , Fig. 7, carries a steady current I_1 . A wire W is provided with ballistic galvanometer G and switch S . When

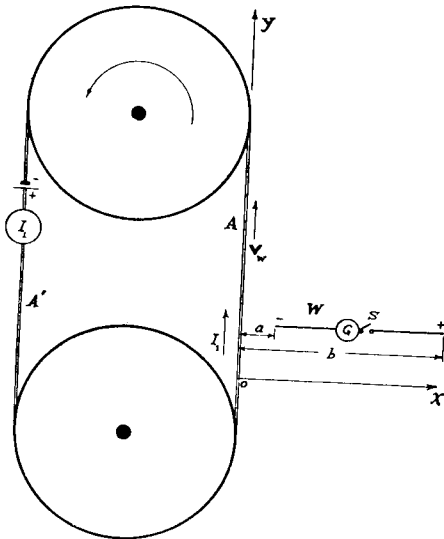


FIG. 7. Determine the induced emf. in W , caused by the longitudinal motion of conductor A .

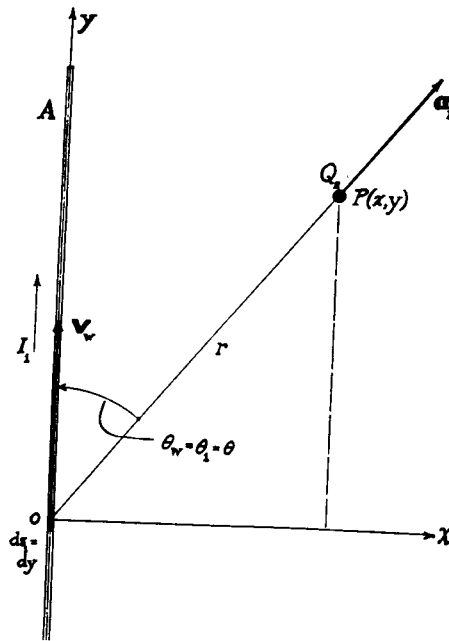


FIG. 8. Analysis of Fig. 7.

A is in uniform motion, S is closed. If an emf. is induced, there will be a momentary deflection of G . Is there an induced emf. in W ?

A Classical Solution

At a given distance x from conductor A , the magnetic flux density is constant, independent of y . Thus the vectors \mathbf{B} along W are independent of time, irrespective of the motion of A . Consequently $\partial\mathbf{B}/\partial t = 0$ and there can be no induced emf., either by transformer action or by flux cutting. This conclusion is also in accordance with Faraday's idea that flux lines are not dragged along by the longitudinal motion of a conductor.

Electrodynamic Solu

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Eq. 2:

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$$= \frac{I_1}{2\pi\epsilon}$$

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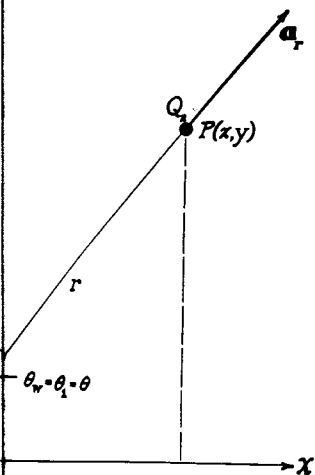
A Classical Solution

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8. Analysis of Fig. 7.

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 Consequently $\partial\mathbf{B}/\partial t = 0$
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Electrodynamic Solution

The force per unit charge at a point (x,y) , Fig. 8, is obtained by using Eq. 2:

$$d\mathbf{F}_2/Q_2 = \mathbf{a}_r \frac{I_1 v_w ds_1}{4\pi\epsilon c^2 r^2} [2 \sin^2\theta - \cos^2\theta].$$

The total effect of conductor A is obtained by integration. The y -component of \mathbf{F}_2 is zero, leaving

$$\begin{aligned} \bar{F}_x &= F_x/Q_2 = \frac{I_1 v_w}{4\pi\epsilon c^2} \int_{-x}^x [2 \sin^2\theta - \cos^2\theta] \sin\theta \frac{dy}{r^3} \\ &= \frac{I_1 v_w}{2\pi\epsilon c^2 x}. \end{aligned} \tag{10}$$

The emf. induced in W is therefore

$$V = \int_a^b \bar{F}_x dx = \frac{I_1 v_w}{2\pi\epsilon c^2} \ln(b/a), \tag{11}$$

which is certainly not zero as predicted by the foregoing classical theory.

6. MOVING BRIDGE

Statement

A metal bridge A floats in two mercury troughs H and H' (Fig. 9). The circuit carries a direct current I . In what direction will the bridge move? This is one of Carl Hering's celebrated experiments (4).

A Classical Solution

It is a well-known experimental fact that a circuit carrying a current tends to expand. For instance, a loop of flexible wire will tend to assume a circular form as the result of electromagnetic forces. In accordance with this principle, *the bridge will move to the right.*

To check this conclusion, consider the direction of the magnetic vector \mathbf{B} . With current as shown in Fig. 9, the entire circuit produces within the loop a magnetic flux that is perpendicular to the diagram and directed into the paper. The force on the bridge is given by the firmly established relation,

$$\mathbf{F} = I \times \mathbf{B}.$$

But if \mathbf{I} in the bridge is downward and \mathbf{B} is into the paper, \mathbf{F} must be to the right for any position of the bridge. This conclusion does not agree with experiment.

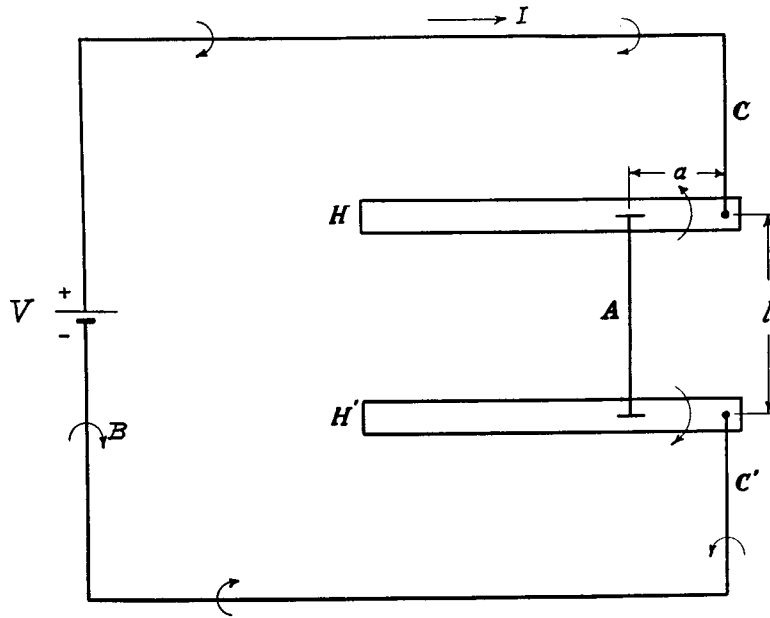


FIG. 9. Motion of metal bridge A floating on mercury troughs H, H'.

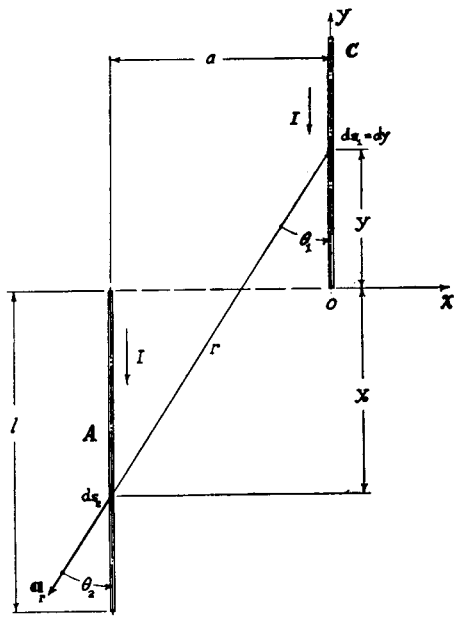


FIG. 10a. Analysis of forces caused by conductor C, Fig. 9.

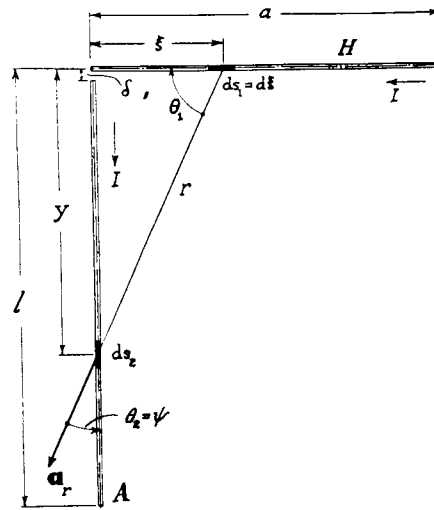


FIG. 10b. Analysis of forces caused by conductor H, Fig. 9.

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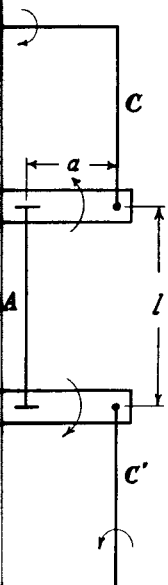
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Analysis of forces caused by
trough H, H' , Fig. 9.

Electrodynamic Solution

The solution requires merely the integration of Eq. 3 around the circuit. This integration is not troublesome in any case, but the ideas can be presented most simply by letting the left part of the circuit expand until its effect on A is negligible. We need consider then only the forces caused by two long vertical conductors C and C' and by the portions of the mercury that are carrying current.

For the conductor C , Fig. 10a, $\eta = 0$ and $\theta_1 = \theta_2 = \theta$, so Eq. 3 becomes

$$d^2\mathbf{F}_2 = -\mathbf{a}_r \frac{I^2 ds_1 ds_2}{4\pi\epsilon c^2 r^2} [2 \sin^2\theta - \cos^2\theta].$$

The force contains both x and y components, but integration over equal, long conductors C and C' will cancel the y -component. Thus the total force on ds_2 , caused by conductor C , is

$$\begin{aligned} d\mathbf{F}_2 &= \mathbf{a}_x \frac{I^2 ds_2}{4\pi\epsilon c^2} \int_0^\infty \frac{2a^3 - a(y + y_0)^2}{r^5} dy \\ &= \mathbf{a}_x \frac{I^2 ds_2}{4\pi\epsilon c^2 a} \left[1 - \frac{y_0^3 + 2y_0 a^2}{(a^2 + y_0^2)^{3/2}} \right]. \end{aligned}$$

The force on the bridge, caused by current in C and C' , is

$$\begin{aligned} \mathbf{F}_2 &= \mathbf{a}_x \frac{I^2}{2\pi\epsilon c^2 a} \int_0^l \left[1 - \frac{y_0^3 + 2y_0 a^2}{(a^2 + y_0^2)^{3/2}} \right] dy_0 \\ &= \mathbf{a}_x \frac{I^2}{2\pi\epsilon c^2 \lambda} \left[1 - \frac{1}{(1 + \lambda^2)^{3/2}} \right], \end{aligned} \tag{12}$$

where $\lambda = a/l$. This force on the bridge is in the positive x -direction and tends to pull the conductor to an equilibrium position at $x = 0$.

Equation 12 applies only to the effect of conductors C and C' . Now take a mercury trough, Fig. 10b. Let $\eta = 0$, $\theta_2 = \psi$, $\theta_1 = -(\pi/2 - \psi)$. Then Eq. 3 becomes

$$d^2\mathbf{F}_2 = \mathbf{a}_r \frac{3I^2 ds_1 ds_2}{4\pi\epsilon c^2 r^2} \sin\psi \cos\psi.$$

Evidently the y -components for H and H' will cancel, leaving only

$$d^2\mathbf{F}_2 = -\mathbf{a}_r \frac{3I^2 ds_1 ds_2}{4\pi\epsilon c^2 r^2} \sin^2\psi \cos\psi.$$

The force on ds_2 , caused by H , is

$$\begin{aligned} d\mathbf{F}_2 &= -\mathbf{a}_x \frac{3I^2 ds_2}{4\pi\epsilon c^2} \int_0^a \frac{y\xi^2}{r^5} d\xi \\ &= -\mathbf{a}_x \frac{I^2 ds_2}{4\pi\epsilon c^2} \frac{a^3}{y(y^2 + a^2)^{\frac{3}{2}}}. \end{aligned}$$

The total force on the bridge, produced by current in H and H' , is therefore

$$\mathbf{F}_2 = -\mathbf{a}_x \frac{I^2 a^3}{2\pi\epsilon c^2} \int_{\delta}^l \frac{dy}{y(y^2 + a^2)^{\frac{3}{2}}}.$$

Since $\delta \ll a$,

$$\mathbf{F}_2 \cong -\mathbf{a}_x \frac{I^2}{2\pi\epsilon c^2} \left[\ln \left(\frac{2a}{\delta} \frac{1}{\lambda + (1 + \lambda^2)^{\frac{1}{2}}} \right) - \left(1 - \frac{\lambda}{(1 + \lambda^2)^{\frac{1}{2}}} \right) \right]. \quad (13)$$

The force caused by current in the mercury elements is always in the negative x -direction. The value of the bracket in Eq. 13 is generally in the neighborhood of +3 or +4. The exact value depends on detailed conditions at the right-angled corners, an analysis of which is not needed here.

The total force on the bridge is expressed as the sum of Eqs. 12 and 13, or

$$\begin{aligned} \mathbf{F}_2 = -\mathbf{a}_x \frac{I^2}{2\pi\epsilon c^2} \left\{ \ln \left(\frac{2a}{\delta} \frac{1}{\lambda + (1 + \lambda^2)^{\frac{1}{2}}} \right) \right. \\ \left. - \frac{1}{\lambda} [1 + \lambda - (1 + \lambda^2)^{\frac{1}{2}}] \right\}. \quad (14) \end{aligned}$$

For comparatively small displacements a , the first term of Eq. 14 predominates and the bridge moves to the left, as found experimentally by Hering (4). But for large displacements, the bridge may move to the right until it reaches an equilibrium position determined by the relation,

$$\ln \left(\frac{2a}{\delta} \frac{1}{\lambda + (1 + \lambda^2)^{\frac{1}{2}}} \right) = \frac{1}{\lambda} [1 + \lambda - (1 + \lambda^2)^{\frac{1}{2}}]. \quad (15)$$

For instance, if the logarithm has the value 4, then

$$4\lambda = 1 + \lambda - (1 + \lambda^2)^{\frac{1}{2}}$$

or

$$\lambda = a/l = \frac{3}{4}.$$

Thus, in this example, the bridge will move to the left until its displace-

ment is $\frac{3}{4}$ of its length
tion.

Statement

A copper disk D
velocity Ω . Direct

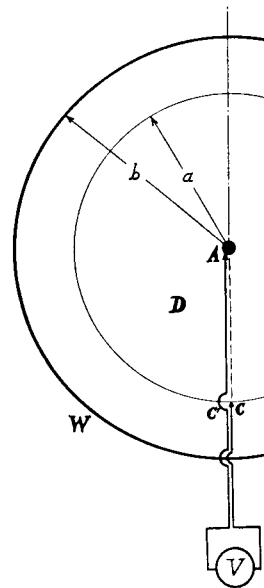


FIG. 11. Unipolar ge
field produced by direct
voltage is generated by ro

netic field. Contact
ductor connects the

- (a) What is the
- (b) If D and W
angular velo
- (c) The disk ar
What is the

A Classical Solution

Start with Max

which is regarded a

ment is $\frac{3}{4}$ of its length. The bridge will remain in this equilibrium position.

Statement

7. UNIPOLAR GENERATOR

A copper disk D (Fig. 11) rotates on its axis A at uniform angular velocity Ω . Direct current I_1 in a stationary loop W produces a mag-

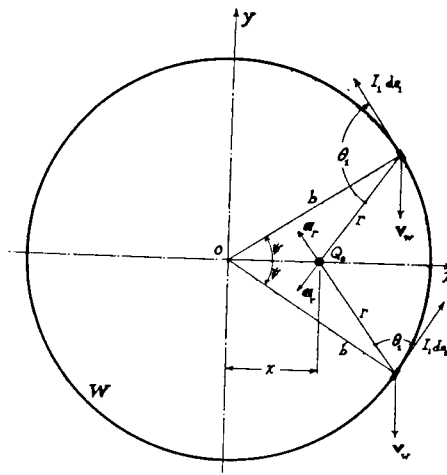
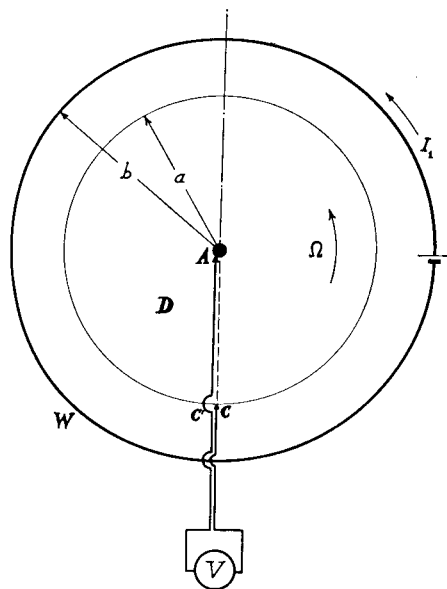


FIG. 11. Unipolar generator. Magnetic field produced by direct current in loop W ; voltage is generated by rotation of disk D .

FIG. 12. Analysis of Fig. 11.

netic field. Contact is made to the disk at A and C , and a bifilar conductor connects these brushes to an electrostatic voltmeter V .

- (a) What is the emf. indicated by the voltmeter?
- (b) If D and W now rotate in the same direction and at the same angular velocity, what is the emf.?
- (c) The disk and voltmeter are stationary and only W rotates. What is the emf.?

A Classical Solution

Start with Maxwell's equation,

$$\text{curl } \mathbf{E} = - \partial \mathbf{B} / \partial t,$$

which is regarded as a cornerstone of electromagnetics, true under all

$d\xi$

$a^2)^{\frac{1}{2}}$

current in H and H' , is

$a^2)^{\frac{1}{2}}$

$$\left(1 - \frac{\lambda}{(1 + \lambda^2)^{\frac{1}{2}}}\right) \quad (13)$$

elements is always in the
 ket in Eq. 13 is generally
 value depends on detailed
 ysis of which is not needed

as the sum of Eqs. 12 and

$$\lambda - (1 + \lambda^2)^{\frac{1}{2}} \quad (14)$$

first term of Eq. 14 pre-
 found experimentally by
 bridge may move to the
 terminated by the relation,

$$- (1 + \lambda^2)^{\frac{1}{2}} \quad (15)$$

then

the left until its displace-

circumstances. Integration over *any closed path* L enclosing an area \mathcal{A} gives

$$\int_a \text{curl } \mathbf{E} \cdot d\mathfrak{A} = \oint_L \mathbf{E} \cdot ds = V = - \int_a \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathfrak{A}.$$

For our closed path, we choose the dotted line AC in the disk and the fixed metallic circuit CVA . But the flux density \mathbf{B} , produced by the steady current I_1 , is certainly time-invariant, so $\partial \mathbf{B} / \partial t = 0$ and

$$V = - \int_a \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathfrak{A} = 0. \tag{16}$$

It is hard to see how anything could be more completely zero than this emf. If the leads to V are directly above each other, there is no flux through the circuit $ACVA$ in any case; if the leads are very close to each other, negligible flux is linked even if they are not above each other; and finally, any flux that does link the circuit is constant, so $\partial \Phi / \partial t = 0$. This conclusion applies to all three cases. But experiment shows an induced emf. in cases (a) and (b).

Suppose that we abandon Maxwell's equation and employ the flux-cutting relation,

$$\mathbf{E} = \mathbf{v} \times \mathbf{B} \quad \text{or} \quad V = Blv.$$

Each element of the metal disk cuts through the magnetic field at velocity $v = \Omega r$, so

$$V = \int_0^a E_r dr = \Omega \int_0^a rB(r) dr. \tag{17}$$

Equation 17 gives the same emf. as that produced by a radial wire, and this result agrees with experiment for case (a).

In (b), however, there is no relative motion between wire and disk, so there is no flux cutting and $V = 0$. Experiment shows, however, that the emf. is the same as in (a). In (c), there is again relative motion between the wire and the disk, so the emf. should be given by Eq. 17. Actually, there is no emf.

Electrodynamic Solution

Equation 2 expresses the force per unit charge acting at any point in the disk because of a current element in W . It is convenient to take the elements in pairs at $\pm \psi$ as shown in Fig. 12. Each element produces a force in the direction of its \mathbf{a}_r . The y -components cancel, leaving only an x -component:

$$d\mathfrak{F} = - \mathbf{a}_x \frac{|I_1|v_w b d\psi}{2\pi\epsilon c^2 r^4} [bx \cos^2\psi + 3bx - 2(b^2 + x^2) \cos\psi](b \cos\psi - x).$$

So at any point

(a) Integration f

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Equation 18
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is as shown in

where R is the
the Ampère fo
 W has been co
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(b) D and W now
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the bifilar con
motion with re
the same as ob
(c) Rotation of W
the conductor
disk, so $V = 0$

Statement

A loop of flexib
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static voltmeter V
way. What is the
To make the pr
special case of Fig.
 y -direction so that
whose axes are sep

